

Cambridge International AS & A Level

PHYSICS		9702/52
Paper 5 Planning, Ar	nalysis and Evaluation	October/November 2023
MARK SCHEME		
Maximum Mark: 30		
	Published	

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Question	Answer	Marks
1	Defining the problem	
	V is the independent variable and z is the dependent variable or vary V and measure z	1
	keep h constant	1
	Methods of data collection	
	labelled diagram of workable experiment including: pulley supported by stand stand placed on surface/bench/floor minimum of two labels from stand, beaker, oil, surface/bench/floor, pulley, string 	1
	use (metre) rule to measure h or (metre) rule correctly positioned with h marked on diagram	1
	use measuring cylinder to measure V	1
	timing method to measure time t of fall of beaker to determine z e.g. use timer/stopwatch or use light gate(s) connected to a timer/data logger	1

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Question	Answer	Marks
1	Method of Analysis	
	plot a graph of $\frac{1}{z^2}$ against $\frac{1}{V}$ or equivalent (e.g. $\frac{1}{V}$ against $\frac{1}{z^2}$) Do not accept logarithms.	1
	$b = \frac{1}{2h \times y\text{-intercept}}$ $a = \frac{1}{2h \times y\text{-intercept}}$	1
	(for $\frac{1}{V}$ against $\frac{1}{z^2}$: $b = \frac{M \times \text{gradient}}{ah}$ or $b = -\frac{\text{gradient}}{2h \times y - \text{intercept}}$)	
	$a = \frac{M}{bh \times \text{gradient}}$ or $a = \frac{2M \times y\text{-intercept}}{\text{gradient}}$	1
	(for $\frac{1}{V}$ against $\frac{1}{z^2}$: $a = -2M \times y$ -intercept)	

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Question	Answer	Marks	
1	Additional detail including safety considerations		
	D1 precaution linked to oil spillage, e.g. use of cushion/sand box/tray for falling beaker to land or use of bungs/lids on beakers or use foam on bench/floor or use foam to prevent rising beaker hitting pulley		
	D2 precaution linked to oil contact with skin e.g. use gloves to avoid contact with oil		
	D3 keep M constant		
	D4 use a (top-pan) balance to measure M		
	D5 method to keep <i>h</i> constant e.g. use a fiducial mark to release the beaker from the same position or release from the same position on the <u>clamped</u> rule each time		
	D6 equation to determine z for method used, e.g. for timing h , $z = 2h/t$ or for one light gate, $z = L/t$ where L is the length of the interrupted beam or for two light gates, $z = \text{distance between light gates}/t$ Do not accept h/t .		
	D7 additional detail on diagram to measure <i>h</i> , e.g. clamp (metre) rule with stand on surface or use of set squares positioned on the surface to side of rule or spirit level positioned to side of rule		
	D8 use large value of h to increase time of fall of beaker		
	D9 repeat measurements of z for the same V and average z		
	D10 relationship valid <u>if</u> a straight line is produced (passing through $\left(\frac{1}{2bh}\right)$)		
	Do not accept line passing through the origin.		

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Question		Ans	swer		Marks
2(a)	gradient = $-\frac{t}{R}$				1
	<i>y</i> -intercept = $\ln I_0 R$				
2(b)		1 / C / 10 ⁴ F ⁻¹	In (V/V)		1
		0.91 or 0.909	0.896 or 0.8961		
		0.76 or 0.758	1.012 or 1.0116		
		0.63 or 0.633	1.115 or 1.1151		
		0.61 or 0.606	1.131 or 1.1314		
		0.48 or 0.482	1.253 or 1.2528		
		0.36 or 0.357	1.348 or 1.3481		
	Values correct as shown above.				
	Uncertainties in In (V/V) from ± 0.021 d	or ± 0.020 to ± 0.010 or	r ± 0.013		1
2(c)(i)	Six points from (b) plotted correctly. Must be within half a small square. Dia	ameter of points must b	pe less than half a smal	l square.	1
	Error bars in In (V/V) plotted correctly. All error bars to be plotted. Total length		ate to less than half a si	mall square and symmetrical.	1

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Question	Answer	Marks
2(c)(ii)	Straight line of best fit drawn. Do not accept line from top point to bottom point. Points must be balanced. Line must pass between (0.820, 0.95) and (0.845, 0.95) and between (0.400, 1.30) and (0.425, 1.30)	1
	Worst acceptable line drawn (steepest or shallowest possible line that passes through all the error bars). All error bars must be plotted.	1
2(c)(iii)	Gradient determined with clear substitution of data points into $\Delta y/\Delta x$. Distance between data points must be greater than half the length of the drawn line. Gradient must be negative.	1
	Gradient determined of worst acceptable line.	1
	uncertainty = (gradient of line of best fit – gradient of worst acceptable line) or uncertainty = ½ (steepest worst line gradient – shallowest worst line gradient)	
2(c)(iv)	y-intercept determined by substitution of correct point with consistent power of ten in m and x into $y = mx + c$.	1

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Question	Answer	Marks
2(d)(i)	R determined using gradient.	1
	$R = -\frac{30.0}{\text{gradient}} = \frac{30.0}{\text{(c)(iii)}}$	
	I_0 determined using y -intercept with method shown.	1
	$I_0 = \frac{e^{y - \text{intercept}}}{R} = \frac{e^{\text{(c)(iv)}}}{\text{(d)(i)}}$	
	R and I_0 determined correctly using gradient and y -intercept and R and I_0 given to 2 or 3 significant figures and R and I_0 given with SI units with appropriate powers of ten.	1
	Units: $R: \Omega$ or s F^{-1} $I_0: A$ or $V F s^{-1}$ or $V \Omega^{-1}$	
2(d)(ii)	Percentage uncertainty in R with method shown.	1
	percentage uncertainty in $R = \left(\frac{\Delta t}{t} + \frac{\Delta \text{gradient}}{\text{gradient}}\right) \times 100$	
	or	
	Correct substitution for max/min methods.	

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Question	Answer	Marks
2(e)	C determined to a minimum of 2 significant figures from (c)(iii) and (c)(iv) or (d)(i) with correct substitutions.	1
	$C = \frac{\text{gradient}}{\ln V - y - \text{intercept}}$ or $C = -\frac{\text{gradient}}{y - \text{intercept} - \ln V}$	
	or	
	$C = -\frac{t}{R(\ln V - \ln I_0 R)}$ or $C = \frac{t}{R(\ln I_0 R - \ln V)}$	

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